

Norms:

- **Definition:** Let (X, F) be a linear vector space. A real-valued function is called a norm (and is denoted by $\|\cdot\|$) if the following properties hold:

- (i) $\|x\| \geq 0$ and $\|x\|=0 \Rightarrow x=0_x$ for each $x \in X$
- (ii) $\|\alpha \cdot x\| = |\alpha| \cdot \|x\|$ for each $x \in X$ and $\alpha \in F$
- (iii) $\|x + y\| \leq \|x\| + \|y\|$ for each $x, y \in X$ (triangle inequality)

- **Examples of norms:**

1. $X = \mathbb{R}^n$ (X is a vector with n elements)

$$\text{1-norm: } \|x\|_1 = \sum_{i=1}^n |x_i|$$

$$\text{2-norm or Euclidean norm: } \|x\|_2 = \sqrt{\sum_{i=1}^n |x_i|^2}$$

$$\infty\text{-norm: } \|x\|_\infty = \max_{1 \leq i \leq n} |x_i|$$

$$\text{p-norm: } \|x\|_p = \sqrt[p]{\sum_{i=1}^n |x_i|^p}$$

2. $X = C[0, T]$ (X is a continuous function in the given interval $[0, T]$)

$$\text{1-norm: } \|x\|_1 = \int_0^T |x(t)| dt$$

$$\text{2-norm or Euclidean norm: } \|x\|_2 = \sqrt{\int_0^T |x(t)|^2 dt}$$

$$\infty\text{-norm: } \|x\|_\infty = \max_{t \in [0, T]} |x(t)|$$

$$\text{p-norm: } \|x\|_p = \sqrt[p]{\int_0^T |x(t)|^p dt}$$

3. $X \in \mathbb{R}^{n \times n}$ (Matrix norms)

$$\text{1-norm: } \|X\|_1 = \max_{1 \leq j \leq n} \sum_{i=1}^n |x_{ij}|$$

$$\text{2-norm or Euclidean norm: } \|X\|_2 = \sqrt{\lambda_{\max}(A^T A)}$$

$$\infty\text{-norm: } \|X\|_\infty = \max_{1 \leq i \leq n} \sum_{j=1}^n |x_{ij}|$$

Gradient Method – Steepest Descent Method:
$$\begin{bmatrix} x_{k+1} \end{bmatrix} = \begin{bmatrix} x_k \end{bmatrix} - \lambda_k^* \begin{bmatrix} \nabla F(x_k) \end{bmatrix}$$

Newton's Method:
$$\begin{bmatrix} x_{k+1} \end{bmatrix} = \begin{bmatrix} x_k \end{bmatrix} - H(x_k)^{-1} \begin{bmatrix} \nabla F(x_k) \end{bmatrix}$$

Exercises:

$$1. \quad (a) \quad \|A_1\|_1 = \max\{1, 3\} = 3 \qquad \|A_1\|_\infty = \max\{3, 1\} = 3$$

$$\|A_1\|_2 = \sqrt[2]{\lambda_{\max}(A_1^T A_1)}$$

$$A_1^T A_1 = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 2 & 5 \end{bmatrix}$$

$$\lambda I - A_1^T A_1 = \begin{bmatrix} \lambda - 1 & -2 \\ -2 & \lambda - 5 \end{bmatrix} \rightarrow \det(\lambda I - A_1^T A_1) = (\lambda - 1)(\lambda - 5) - 4$$

$$= \lambda^2 - 6\lambda + 5 - 4 = \lambda^2 - 6\lambda + 1$$

$$\lambda_{1,2} = \frac{6 \pm \sqrt{36 - 4}}{2} = \frac{6 \pm \sqrt{32}}{2} = \frac{6 \pm 2\sqrt{8}}{2} = 3 \pm \sqrt{8}$$

$$\rightarrow \lambda_1 = 3 + \sqrt{8} = 5.828 \qquad \lambda_2 = 3 - \sqrt{8} = 0.172$$

$$\rightarrow \lambda_{\max} = \max\{\lambda_1, \lambda_2\} = \lambda_1 = 5.828$$

$$\rightarrow \|A_1\|_2 = \sqrt[2]{5.828} = 2.414$$

$$(b) \quad \|A_2\|_1 = \max\{4, 6\} = 6 \qquad \|A_2\|_\infty = \max\{3, 7\} = 7$$

$$\|A_2\|_2 = \sqrt[2]{\lambda_{\max}(A_2^T A_2)}$$

$$A_2^T A_2 = \begin{bmatrix} 1 & 3 \\ 2 & -4 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & -4 \end{bmatrix} = \begin{bmatrix} 10 & -10 \\ -10 & 20 \end{bmatrix}$$

$$\lambda I - A_2^T A_2 = \begin{bmatrix} \lambda - 10 & 10 \\ 10 & \lambda - 20 \end{bmatrix} \rightarrow \det(\lambda I - A_2^T A_2) = (\lambda - 10)(\lambda - 20) - 100$$

$$= \lambda^2 - 30\lambda + 200 - 100 = \lambda^2 - 30\lambda + 100$$

$$\lambda_{1,2} = \frac{30 \pm \sqrt{30^2 - 400}}{2} = 15 \pm 5\sqrt{5}$$

$$\rightarrow \lambda_1 = 15 + 5\sqrt{5} = 26.18 \qquad \lambda_2 = 15 - 5\sqrt{5} = 3.82$$

$$\rightarrow \lambda_{\max} = \max\{\lambda_1, \lambda_2\} = \lambda_1 = 26.18$$

$$\rightarrow \|A_2\|_2 = \sqrt[2]{26.18} = 5.117$$

2. (a) $f(x) = x_1^2 + x_2^2 - x_1$

$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \end{bmatrix} = \begin{bmatrix} 2x_1 - 1 \\ 2x_2 \end{bmatrix} = 0 \rightarrow \begin{matrix} 2x_1 - 1 = 0 \rightarrow x_1 = \frac{1}{2} \\ 2x_2 = 0 \rightarrow x_2 = 0 \end{matrix}$$

$$\nabla^2 f = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \rightarrow \det(\nabla^2 f) = 4 - 0 = 4 > 0$$

$\nabla^2 f$ is a positive definite $\rightarrow \left(\frac{1}{2}, 0\right)$ is a minimum

(b) $f(x) = x_1^4 + x_1 x_2 + \frac{1}{2} x_2^2$

$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \end{bmatrix} = \begin{bmatrix} 4x_1^3 + x_2 \\ x_1 + x_2 \end{bmatrix} = 0 \rightarrow \begin{matrix} 4x_1^3 + x_2 = 0 \rightarrow 4x_1^3 - x_1 = x_1(4x_1^2 - 1) = 0 \\ x_1 + x_2 = 0 \rightarrow x_2 = -x_1 \end{matrix}$$

$$x_1 = 0 \rightarrow x_2 = 0$$

$$x_1 = \pm \frac{1}{2} \rightarrow x_2 = \mp \frac{1}{2}$$

Points: $(0,0), \left(\frac{1}{2}, -\frac{1}{2}\right), \left(-\frac{1}{2}, \frac{1}{2}\right)$

$$\nabla^2 f = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} \end{bmatrix} = \begin{bmatrix} 12x_1^2 & 1 \\ 1 & 1 \end{bmatrix}$$

$$\nabla^2 f|_{(0,0)} = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} \rightarrow \det = 0 - 1 = -1 < 0 \rightarrow \text{negative definite}$$

$\rightarrow (0,0)$ is not a minimum

$$\nabla^2 f|_{\left(\frac{1}{2}, -\frac{1}{2}\right)} = \nabla^2 f|_{\left(-\frac{1}{2}, \frac{1}{2}\right)} = \begin{bmatrix} 3 & 1 \\ 1 & 1 \end{bmatrix} \rightarrow \det = 3 - 1 = 2 > 0 \rightarrow \text{positive definite}$$

$\rightarrow \left(\frac{1}{2}, -\frac{1}{2}\right)$ and $\left(-\frac{1}{2}, \frac{1}{2}\right)$ are minimum points

(c) $f(x) = x_1^2 + 2x_2^2 + 4x_1 + 4x_2$

$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \end{bmatrix} = \begin{bmatrix} 2x_1 + 4 \\ 4x_2 + 4 \end{bmatrix} = 0 \rightarrow \begin{matrix} 2x_1 + 4 = 0 \rightarrow x_1 = -2 \\ 4x_2 + 4 = 0 \rightarrow x_2 = -1 \end{matrix} \rightarrow (-2, -1)$$

$$\nabla^2 f = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 4 \end{bmatrix} \rightarrow \det(\nabla^2 f) = 8 - 0 = 8 > 0$$

$\nabla^2 f$ is a positive definite $\rightarrow (-2, -1)$ is a minimum

$$(d) f(x) = 4x_1^2 - 2x_1^4 + \frac{1}{3}x_1^6 + x_1x_2 + \frac{1}{4}x_2^2$$

$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \end{bmatrix} = \begin{bmatrix} 8x_1 - 8x_1^3 + 2x_1^5 + x_2 \\ x_1 + \frac{1}{2}x_2 \end{bmatrix} = 0 \rightarrow x_1 + \frac{1}{2}x_2 = 0 \rightarrow x_2 = -2x_1$$

$$\rightarrow 8x_1 - 8x_1^3 + 2x_1^5 + x_2 = 0 \rightarrow 8x_1 - 8x_1^3 + 2x_1^5 - 2x_1 = 6x_1 - 8x_1^3 + 2x_1^5 = 0$$

$$\rightarrow 2x_1(x_1^4 - 4x_1^2 + 3) = 2x_1(x_1^2 - 3)(x_1^2 - 1) = 0$$

$$\rightarrow x_1 = 0 \rightarrow x_2 = 0$$

$$\rightarrow x_1 = \pm\sqrt{3} \rightarrow x_2 = \mp 2\sqrt{3}$$

$$\rightarrow x_1 = \pm 1 \rightarrow x_2 = \mp 2$$

Points: $(0,0), (\sqrt{3}, -2\sqrt{3}), (-\sqrt{3}, 2\sqrt{3}), (1, -2), (-1, 2)$

$$\nabla^2 f = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} \end{bmatrix} = \begin{bmatrix} 8 - 24x_1^2 + 10x_1^4 & 1 \\ 1 & \frac{1}{2} \end{bmatrix}$$

$$\nabla^2 f|_{(0,0)} = \begin{bmatrix} 8 & 1 \\ 1 & 1/2 \end{bmatrix} \rightarrow \det = 4 - 1 = 3 > 0 \rightarrow \text{positive definite} \rightarrow (0,0) \text{ is a minimum}$$

$$\nabla^2 f|_{(1,-2)} = \nabla^2 f|_{(-1,2)} = \begin{bmatrix} -6 & 1 \\ 1 & \frac{1}{2} \end{bmatrix} \rightarrow \det = -3 - 1 = -4 < 0 \rightarrow \text{negative definite}$$

$\rightarrow (1, -2)$ and $(-1, 2)$ are not minimum points

$$\nabla^2 f|_{(\sqrt{3}, -2\sqrt{3})} = \nabla^2 f|_{(-\sqrt{3}, 2\sqrt{3})} = \begin{bmatrix} 26 & 1 \\ 1 & \frac{1}{2} \end{bmatrix} \rightarrow \det = 13 - 1 = 12 < 0 \rightarrow \text{positive definite}$$

$\rightarrow (\sqrt{3}, -2\sqrt{3})$ and $(-\sqrt{3}, 2\sqrt{3})$ are minimum points

3. Find the point on the line $3x + 2y = 5$ in two-dimensional space closest to the origin when distance is measured by each of the following three norms:
- The 1-norm
 - The 2-norm
 - The ∞ -norm

Solution:

$$3x + 2y = 5 \Rightarrow x = a \Rightarrow y = \frac{5 - 3a}{2}$$

Any point on the line $3x + 2y = 5$ can be represented by $z = \begin{bmatrix} a \\ \frac{5 - 3a}{2} \end{bmatrix}$

We are going to use the following equations given on the first page, as we consider z to be a vector with 2 elements and represents any point on the line $3x + 2y = 5$.

$z \in \mathbb{R}^2$ (z is a vector with 2 elements) 1-norm: $\ z\ _1 = \sum_{i=1}^n z_i $ 2-norm or Euclidean norm: $\ z\ _2 = \sqrt{\sum_{i=1}^n z_i ^2}$ ∞ -norm: $\ z\ _\infty = \max_{1 \leq i \leq n} z_i $

1-norm:

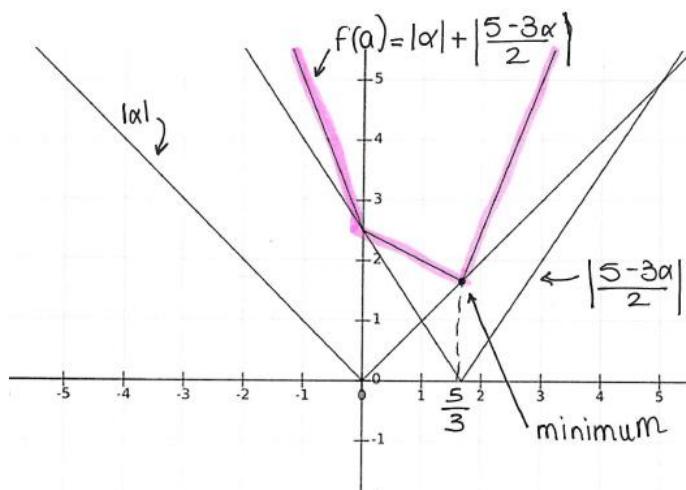
Distance in 1-norm of z from origin is $\|z_1\| = |a| + \left| \frac{5-3a}{2} \right|$

We want to find a that minimizes $f(a) = |a| + \left| \frac{5-3a}{2} \right|$

Note: This is a non-smooth optimization problem, so we cannot take derivatives.

We can obtain the minimum by sketching $f(a)$ and it occurs at $a = \frac{5}{3}$.

$\|z_1\|$ is minimized at $z^* = \begin{bmatrix} 5/3 \\ 0 \end{bmatrix}$



2-norm:

(smooth problem, we can take derivatives)

Distance in 2-norm of z from origin is $\|z_2\| = \sqrt{a^2 + \left(\frac{5-3a}{2}\right)^2} \Rightarrow F(a) = a^2 + \left(\frac{5-3a}{2}\right)^2$

$$\frac{\partial F}{\partial a} = 0 \Rightarrow 2a + 2\left(\frac{-3}{2}\right)\left(\frac{5-3a}{2}\right) = 0 \Rightarrow 2a - \frac{15}{2} + \frac{9a}{2} = 0 \Rightarrow \boxed{a = \frac{15}{13}}$$

$$\frac{\partial^2 F}{\partial a^2} = \frac{13}{2} > 0 \Rightarrow z = \begin{bmatrix} 15/13 \\ 10/13 \end{bmatrix} \Rightarrow \|z_2\| \text{ is minimize at } z = \begin{bmatrix} 15/13 \\ 10/13 \end{bmatrix}.$$

∞ -norm:

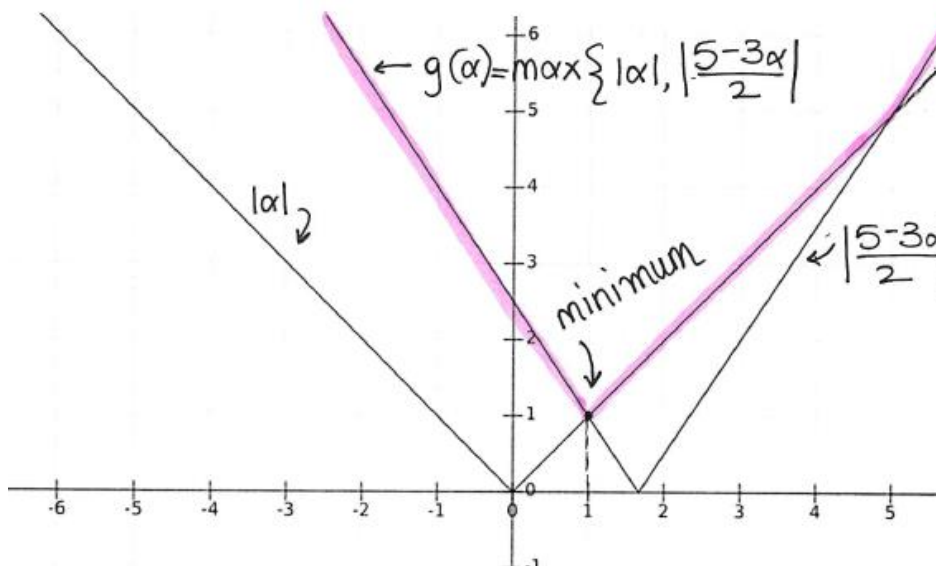
Again, it is a non-smooth optimization problem, so by sketching $g(a)$ we can obtain the minimum.

$$\|z_\infty\| = \max\left\{|a|, \left|\frac{5-3a}{2}\right|\right\}$$

Find a that minimizes $g(a) = \max\left\{|a|, \left|\frac{5-3a}{2}\right|\right\}$

$g(a)$ is minimized at a^* where $a^* = \frac{5-3a}{2} \Rightarrow \boxed{a^* = 1} \Rightarrow z = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$\|z_\infty\|$ is minimized at $z^* = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$



4. (a) Let $x = [x_1 \ x_2 \ x_3]^T$ and $F(x) = x_1x_2^2 + x_2x_3^2 + x_3^3$. Compute the Gradient and Hessian of F and find all values x^* for which $\nabla F(x^*) = 0$.

Is the Hessian singular or nonsingular at these values?

(b) Using the first order necessary conditions ($\nabla F(x^*) = 0$) find a minimum point of the function:

$$F(x_1, x_2, x_3) = 2x_1^2 + x_1x_2 + x_2^2 + x_2x_3 + x_3^2 - 6x_1 - 7x_2 - 8x_3 + 9.$$

Verify that this point is a minimum by checking the second order sufficiency conditions.

Solution:

(a)

$$\text{Gradient} = \nabla F = \begin{bmatrix} \frac{\partial F}{\partial x_1} \\ \frac{\partial F}{\partial x_2} \\ \frac{\partial F}{\partial x_3} \end{bmatrix} = \begin{bmatrix} x_2^2 \\ x_3^2 + 2x_1x_2 \\ 2x_2x_3 + 3x_3^2 \end{bmatrix}$$

$$\text{Hessian} = \nabla^2 F = \begin{bmatrix} \frac{\partial^2 F}{\partial x_1^2} & \frac{\partial^2 F}{\partial x_1 \partial x_2} & \frac{\partial^2 F}{\partial x_1 \partial x_3} \\ \frac{\partial^2 F}{\partial x_2 \partial x_1} & \frac{\partial^2 F}{\partial x_2^2} & \frac{\partial^2 F}{\partial x_2 \partial x_3} \\ \frac{\partial^2 F}{\partial x_3 \partial x_1} & \frac{\partial^2 F}{\partial x_3 \partial x_2} & \frac{\partial^2 F}{\partial x_3^2} \end{bmatrix} = \begin{bmatrix} 0 & 2x_2 & 0 \\ 2x_2 & 2x_1 & 2x_3 \\ 0 & 2x_3 & 2x_2 + 6x_3 \end{bmatrix}$$

$$\nabla F(x^*) = 0 \Rightarrow \left. \begin{array}{l} x_2^2 = 0 \\ 2x_1x_2 + x_3^2 = 0 \\ 2x_2x_3 + 3x_3^2 = 0 \end{array} \right\} \Rightarrow \begin{array}{l} x_1^* = a \\ x_2^* = 0 \\ x_3^* = 0 \end{array} \Rightarrow x^* = \begin{bmatrix} a \\ 0 \\ 0 \end{bmatrix}, a \in \mathbb{R}$$

$$\nabla^2 F(x^*) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 2a & 0 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \det(\nabla^2 F(x^*)) = 0 \Rightarrow \text{Hessian is singular}$$

[A matrix is singular if the determinant of the matrix is equal to zero.]

(b)

$$\text{Gradient} = \nabla F(x) = \begin{bmatrix} \frac{\partial F}{\partial x_1} \\ \frac{\partial F}{\partial x_2} \\ \frac{\partial F}{\partial x_3} \end{bmatrix} = \begin{bmatrix} 4x_1 + x_2 - 6 \\ x_1 + 2x_2 + x_3 - 7 \\ x_2 + 2x_3 \end{bmatrix} \Rightarrow \nabla F(x^*) = 0 \Rightarrow \begin{array}{l} 4x_1^* + x_2^* - 6 = 0 \\ x_1^* + 2x_2^* + x_3^* - 7 = 0 \\ x_2^* + 2x_3^* - 8 = 0 \end{array}$$

Solve the equations:

$$4x_1^* + x_2^* - 6 = 0 \quad (1)$$

$$x_1^* + 2x_2^* + x_3^* - 7 = 0 \quad (2)$$

$$x_2^* + 2x_3^* - 8 = 0 \quad (3)$$

$$\left. \begin{array}{l} 4x_1 + x_2 = 6 \quad (1) \\ x_2 = 8 - 2x_3 \quad (3) \end{array} \right\} \Rightarrow 4x_1 = 6 - x_2 \Rightarrow (3) \rightarrow (1) \Rightarrow 4x_1 = 6 - 8 + 2x_3 \Rightarrow 4x_1 = 2x_3 - 2$$

$$\Rightarrow x_1 = \frac{1}{2}(x_3 - 1) \quad (4)$$

$$(4) \rightarrow (2) \Rightarrow \frac{1}{2}(x_3 - 1) + 16 - 4x_3 + x_3 - 7 = 0 \Rightarrow x_3 - 1 + 32 - 8x_3 + 2x_3 - 14 = 0$$

$$\Rightarrow -5x_3 + 17 = 0 \Rightarrow \boxed{x_3 = \frac{17}{5}} \quad (5)$$

$$(5) \rightarrow (3) \Rightarrow x_2 = 8 - 2\left(\frac{17}{5}\right) \Rightarrow \boxed{x_2 = \frac{6}{5}} \quad (6)$$

$$(5) \rightarrow (4) \Rightarrow x_1 = \frac{1}{2}\left(\frac{17}{5} - 1\right) = \frac{12}{5} \times \frac{1}{2} \Rightarrow \boxed{x_1 = \frac{6}{5}} \Rightarrow \boxed{x^* = \begin{bmatrix} 6/5 \\ 6/5 \\ 17/5 \end{bmatrix}}$$

$$Hessian = \nabla^2 F(x) = \begin{bmatrix} \frac{d^2 F}{\partial x_1^2} & \frac{\partial^2 F}{\partial x_1 \partial x_2} & \frac{\partial^2 F}{\partial x_1 \partial x_3} \\ \frac{\partial^2 F}{\partial x_2 \partial x_1} & \frac{d^2 F}{\partial x_2^2} & \frac{\partial^2 F}{\partial x_2 \partial x_3} \\ \frac{\partial^2 F}{\partial x_3 \partial x_1} & \frac{\partial^2 F}{\partial x_3 \partial x_2} & \frac{d^2 F}{\partial x_3^2} \end{bmatrix} = \begin{bmatrix} 4 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 2 \end{bmatrix} \Rightarrow \nabla^2 F(x^*) = \begin{bmatrix} 4 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 2 \end{bmatrix}$$

$$\lambda_1 = 0.8299$$

Eigenvalues (calculated using Matlab) are: $\lambda_2 = 2.6889$

$$\lambda_3 = 4.4812$$

All eigenvalues are positive, $\lambda_i(A) > 0 \Rightarrow \nabla^2 F(x^*) > 0$, *positive definite* $\Rightarrow x^*$ is a minimum

5. Write a script to implement the Gradient method – Steepest Descent Method for minimizing the function:

$$F(x_1, x_2) = e^{x_1}(4x_1^2 + 2x_2^2 + 4x_1x_2 + 2x_2 + 1).$$

Let your initial estimate be something close to the origin. Choose the step-size λ to be a constant. Run a few simulations with different values of λ to see what happens as you vary the step-size from a small to a large value.

Solution:

$$\nabla F(x_1, x_2) = \begin{bmatrix} \frac{\partial F}{\partial x_1} \\ \frac{\partial F}{\partial x_2} \end{bmatrix} = \begin{bmatrix} e^{x_1}(4x_1^2 + 2x_2^2 + 4x_1x_2 + 6x_2 + 8x_1 + 1) \\ e^{x_1}(4x_2 + 4x_1 + 2) \end{bmatrix}$$

$$\text{Gradient Method – Steepest Descent Method: } \begin{bmatrix} x_{k+1} \end{bmatrix} = \begin{bmatrix} x_k \end{bmatrix} - \lambda_k^* \begin{bmatrix} \nabla F(x_k) \end{bmatrix}$$

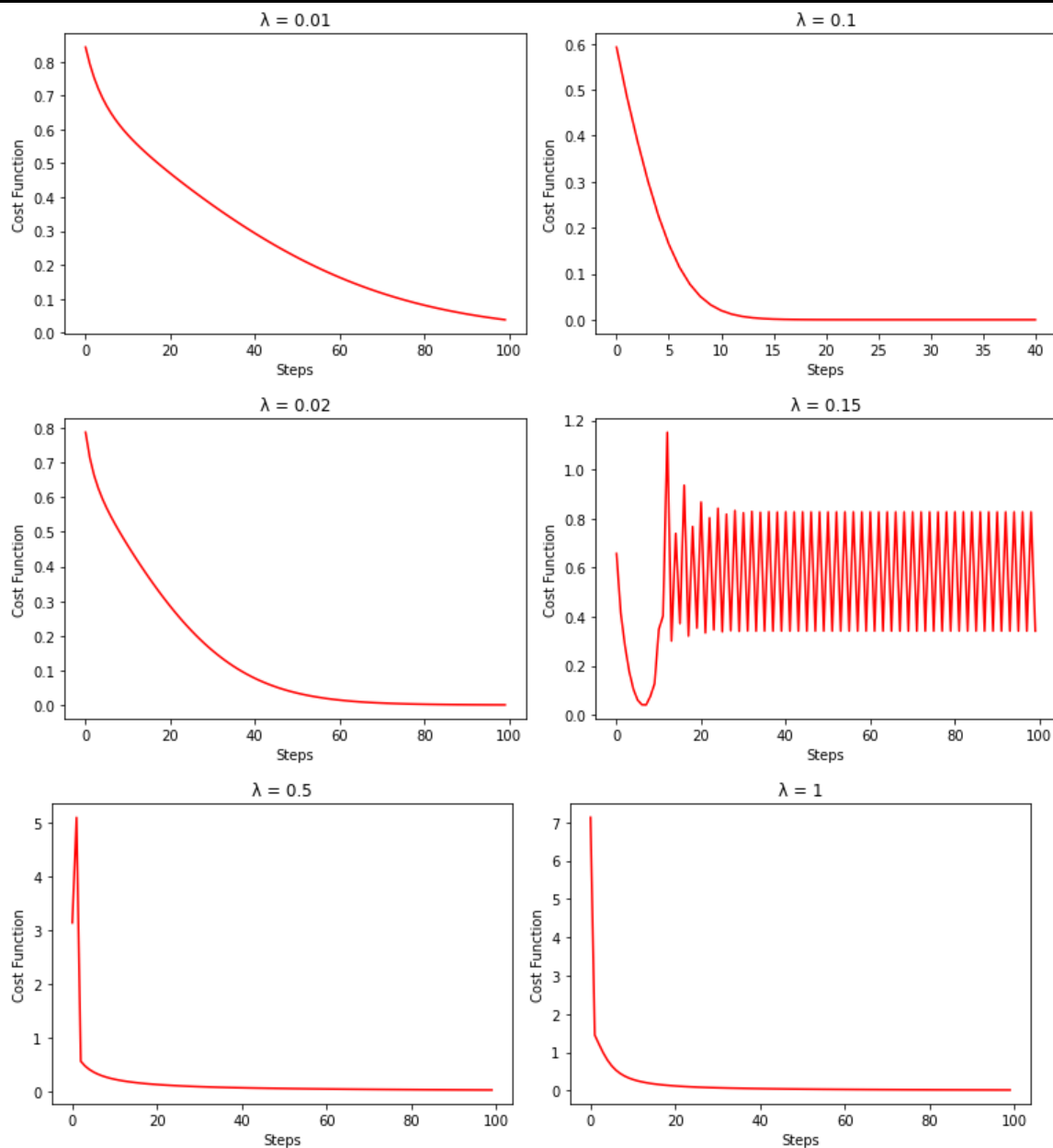
```
import numpy as np
import pandas as pd
import math
import matplotlib.pyplot as plt
```

```
def my_function(x):
    z = math.exp(x[0]) * (4*x[0]**2 + 2*x[1]**2 + 4*x[0]*x[1]+2*x[1]+1)
    return z
def gradient1(x):
    z = math.exp(x[0]) * (4*x[0]**2 + 2*x[1]**2 + 4*x[0]*x[1] + 8*x[0] + 6*x[1] + 1)
    return z
def gradient2(x):
    z = math.exp(x[0]) * (4*x[0] + 4*x[1] + 2)
    return z
l = 1
tolerance = 0.000000001
maxsteps = 100
cost_function = np.zeros((1,maxsteps))
x = np.zeros((1,maxsteps))
y = np.zeros((1,maxsteps))
x_initial1 = 0.1
x_initial2 = -0.1
count = 0
w = [x_initial1, x_initial2]
x[0,count] = w[0]
y[0,count] = w[1]
cost_function[count] = my_function(w)
while ((count<maxsteps)&(abs(my_function(w))>tolerance)):
    d = [gradient1(w), gradient2(w)]
    w[0] = w[0] - l * d[0]
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w[1] = w[1] - l * d[1]
x[0, count] = w[0]
y[0, count] = w[1]
cost_function[0, count] = my_function(w)
count = count + 1
plt.plot([r for r in range(count)], cost_function[0,:count], 'r-')
plt.xlabel('Steps')
plt.ylabel('Cost Function')
plt.title('λ = 1')
plt.show()

```



It can be seen that the rate of convergence keeps increasing as λ increases until about $\lambda = 0.1$ in which oscillations are not observed. If we choose $\lambda = 0.15$ we observe some oscillations.