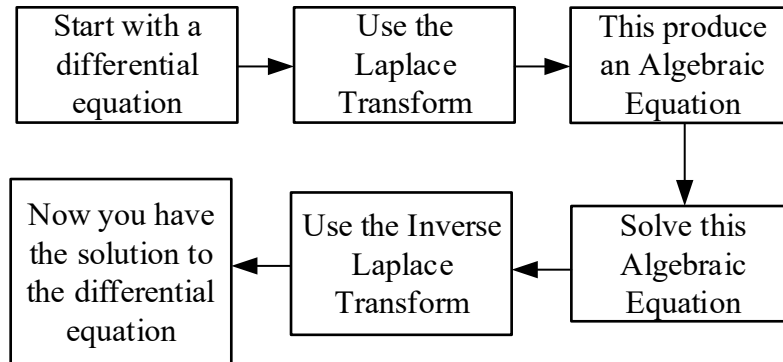


Tutorial 1

ECE 804-Laplace Transform

The Laplace transform is used to solve certain differential equations. The basic idea is:



Definition: The Laplace transform of a general signal $x(t)$ is defined as,

$$X(s) \triangleq \int_{-\infty}^{+\infty} x(t)e^{-st} dt$$

where s is a complex variable which can be written as $s = \sigma + j\omega$, with σ and ω the real and imaginary parts, respectively.

Example 1: Compute the Laplace transform of $x(t) = e^{-2t}1(t)$

From the definition,

$$X(s) = \int_{-\infty}^{+\infty} e^{-2t}1(t)e^{-st} dt = \int_0^{+\infty} e^{-(s+2)t} dt = \left[-\frac{1}{s+2} e^{-(s+2)t} \right]_0^{\infty} = \frac{1}{s+2}$$

Example 2: Compute the Laplace transform of $x(t) = \cos(\omega_o t)1(t)$

$$\begin{aligned} X(s) &= \int_{-\infty}^{+\infty} \cos(\omega_o t)1(t)e^{-st} dt = \\ &= \int_0^{+\infty} \frac{e^{j\omega_o t} + e^{-j\omega_o t}}{2} e^{-st} dt = \\ &= \frac{1}{2} \left[\left[-\frac{1}{s-j\omega_o} e^{-(s-j\omega_o)t} \right]_0^{\infty} - \left[-\frac{1}{s+j\omega_o} e^{-(s+j\omega_o)t} \right]_0^{\infty} \right] = \\ &= \frac{1}{2} \left[\frac{1}{s-j\omega_o} + \frac{1}{s+j\omega_o} \right] = \frac{s}{s^2 + \omega_o^2} \end{aligned}$$

Example 3: Compute the Laplace transform of $x(t) = \sin(\omega_o t)1(t)$

$$\begin{aligned} X(s) &= \int_{-\infty}^{+\infty} \sin(\omega_o t)1(t)e^{-st} dt = \\ &= \int_0^{+\infty} \frac{e^{j\omega_o t} - e^{-j\omega_o t}}{2j} e^{-st} dt = \\ &= \frac{1}{2j} \left[\left[-\frac{1}{s - j\omega_o} e^{-(s-j\omega_o)t} \right]_0^{\infty} + \left[\frac{1}{s + j\omega_o} e^{-(s+j\omega_o)t} \right]_0^{\infty} \right] = \\ &= \frac{1}{2j} \left[\frac{1}{s - j\omega_o} + \frac{1}{s + j\omega_o} \right] = \frac{\omega_o}{s^2 + \omega_o^2} \end{aligned}$$

Basic Properties of Laplace transform:

- *superposition principle*
 $z(t) = ax(t) + by(t) \xrightarrow{\text{Laplace}} Z(s) = aX(s) + bY(s)$
- *Time shifting*
 $x(t) \xrightarrow{\text{Laplace}} X(s)$
 $x(t - t_0) \xrightarrow{\text{Laplace}} e^{-st_0} X(s)$
- *Laplace transform of 1st -order derivative of $x(t)$*
 $y(t) = \frac{dx(t)}{dt} \xrightarrow{\text{Laplace}} Y(s) = sX(s) - x(0)$
- *Laplace transform of 2nd -order derivative of $x(t)$*
 $y(t) = \frac{dx^2(t)}{dt^2} \xrightarrow{\text{Laplace}} Y(s) = s^2 X(s) - sx(0) - \frac{dx(0)}{dt}$

Example 4: Determine $X_3(s) = X_1(s) - X_2(s)$

$$\begin{aligned} X_1(s) &= \frac{1}{s+1}, X_2(s) = \frac{1}{(s+1)(s+2)} \\ \Rightarrow X_3(s) &= X_1(s) - X_2(s) \\ &= \frac{s+1}{(s+1)(s+2)} = \frac{1}{s+2} \end{aligned}$$

Example 5: Determine the Laplace transform of $e^{-2(t+3)}1(t+3)$

$$\begin{aligned} e^{-2t}1(t) &\xrightarrow{\text{Laplace}} \frac{1}{s+2} \\ e^{-2(t+3)}1(t+3) &\xrightarrow{\text{Laplace}} \frac{e^{3s}}{s+2} \end{aligned}$$

Poles-zero map

In the most of the practical cases, the Laplace transform is a rational function of s :

$$X(s) = \frac{N(s)}{D(s)}$$

- roots of nominator are called **zeros** ($N(s)=0$)
- roots of denominator are called **poles** ($D(s)=0$)

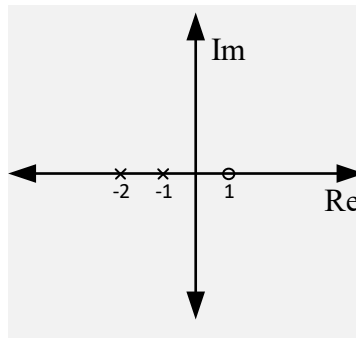
The representation of Laplace transform can be done in the complex plane s by placing the poles and zeros.

- Zeros: o
- Poles: x

Example 6: Plot the pole-zero map of the signal $x(t) = 3e^{-2t}1(t) - 2e^{-t}1(t)$.

Laplace transform of $x(t)$ is:

$$X(s) = \frac{3}{s+2} - \frac{2}{s+1} = \frac{s-1}{(s+2)(s+1)}$$



Inverse Laplace transform Definition:

$$x(t) = \frac{1}{2\pi j} \int_{\sigma+j\infty}^{\sigma-j\infty} X(s)e^{st} ds$$

The estimation of the inverse Laplace transform is performed using known Laplace transforms and partial fractions and not by the definition.

Example 7:

Determine the inverse Laplace transform of $X(s)$

$$X(s) = \frac{s+3}{(s+1)(s-2)} = \frac{A}{s+1} + \frac{B}{s-2}$$

For estimating A and B,

$$s + 3 = (s - 2)A + (s + 1)B$$

$$s = 2 \Rightarrow B = \frac{5}{3}$$

$$s = -1 \Rightarrow A = -\frac{2}{3}$$

Therefore, using known Laplace transforms

$$e^{-at} 1(t) \xrightarrow{\text{Laplace}} \frac{1}{s+a}$$

$$X(s) = \frac{s+3}{(s+1)(s-2)} = \frac{-\frac{2}{3}}{s+1} + \frac{\frac{5}{3}}{s-2}$$

$$x(t) = -\frac{2}{3} e^{-t} 1(t) + \frac{5}{3} e^{2t} 1(t)$$

Further Questions:

Question 1: Determine the Laplace transform of the following function of time using the table of Laplace transforms (see next page).

(a) $x(t) = 4 \cos 9t - 5t + 2e^{3t} 1(t)$

(b) $x(t) = e^{-4t} 1(t) + e^{-5t} (\sin 5t) 1(t)$

Question 2: Determine the function of time $x(t)$, for each of the following Laplace transforms.

(a) $X(s) = \frac{1}{s+1}$

(b) $X(s) = \frac{1}{s^2+9}$

(c) $X(s) = \frac{s+2}{s^2+7s+9}$

Question 3: Consider the signals $x(t)$ and $y(t)$ related through the differential equations.

$$\frac{dx(t)}{dt} = -2y(t) + \delta(t)$$

and

$$\frac{dy(t)}{dt} = 2x(t)$$

Determine $Y(s)$ and $X(s)$.

Tutorial 1

ECE804-Laplace Transform-Solutions

Question 1:

(a)

$$\cos(\omega t) \xrightarrow{\text{Laplace}} \frac{s}{s^2 + \omega^2}$$

$$t \xrightarrow{\text{Laplace}} \frac{1}{s^2}$$

$$e^{at}u(t) \xrightarrow{\text{Laplace}} \frac{1}{s-a}$$

$$X(s) = 4 \frac{s}{s^2 + 2^2} - 5 \frac{1}{s^2} + \frac{2}{s-3} = \frac{6s^4 - 17s^3 + 23s^2 - 20s + 60}{s^5 - 3s^4 + 4s^3 - 12s^2}$$

(b)

$$e^{at}u(t) \xrightarrow{\text{Laplace}} \frac{1}{s-a}$$

$$e^{at} \sin(\omega t)u(t) \xrightarrow{\text{Laplace}} \frac{\omega}{(s-a)^2 + \omega^2}$$

$$X(s) = \frac{1}{s+4} + \frac{5}{(s+5)^2 + 25} = \frac{s^2 + 15s + 70}{s^3 + 14s^2 + 90s + 100}$$

Question 2:

(a) From table $x(t) = e^{-t}u(t)$

(b) From table $x(t) = \frac{1}{3} \sin(3t)u(t)$

(c) Using partial fraction expansion

$$X(s) = \frac{s+2}{s^2 + 7s + 12} = \frac{A}{s+4} + \frac{B}{s+3}$$

$$A = 2, B = -1$$

$$x(t) = 2e^{-4t}u(t) - e^{-3t}u(t)$$

Question 3:

Taking the Laplace transforms of both sides of the two differential equations, we have

$$sX(s) = -2Y(s) + 1 \quad \text{and} \quad sY(s) = 2X(s)$$

Solving for $X(s)$ and $Y(s)$, we obtain

$$X(s) = \frac{s}{s^2 + 4} \text{ and } Y(s) = 2s^2 + 4$$

Table of Laplace Transforms

| | |
|---|---|
| $f(t)$ | $F(s) = \int_0^{\infty} f(t)e^{-st} dt$ |
| $f + g$ | $F + G$ |
| αf ($\alpha \in \mathbf{R}$) | αF |
| $\frac{df}{dt}$ | $sF(s) - f(0)$ |
| $\frac{d^k f}{dt^k}$ | $s^k F(s) - s^{k-1}f(0) - s^{k-2}\frac{df}{dt}(0) - \dots - \frac{d^{k-1}f}{dt^{k-1}}(0)$ |
| $g(t) = \int_0^t f(\tau) d\tau$ | $G(s) = \frac{F(s)}{s}$ |
| $f(\alpha t)$, $\alpha > 0$ | $\frac{1}{\alpha}F(s/\alpha)$ |
| $e^{at}f(t)$ | $F(s - a)$ |
| $tf(t)$ | $-\frac{dF}{ds}$ |
| $t^k f(t)$ | $(-1)^k \frac{d^k F(s)}{ds^k}$ |
| $\frac{f(t)}{t}$ | $\int_s^{\infty} F(s) ds$ |
| $g(t) = \begin{cases} 0 & 0 \leq t < T \\ f(t - T) & t \geq T \end{cases}$, $T \geq 0$ | $G(s) = e^{-sT} F(s)$ |

| | |
|----------------------------|---|
| 1 | $\frac{1}{s}$ |
| δ | 1 |
| $\delta^{(k)}$ | s^k |
| t | $\frac{1}{s^2}$ |
| $\frac{t^k}{k!}, k \geq 0$ | $\frac{1}{s^{k+1}}$ |
| e^{at} | $\frac{1}{s-a}$ |
| $\cos \omega t$ | $\frac{s}{s^2 + \omega^2} = \frac{1/2}{s - j\omega} + \frac{1/2}{s + j\omega}$ |
| $\sin \omega t$ | $\frac{\omega}{s^2 + \omega^2} = \frac{1/2j}{s - j\omega} - \frac{1/2j}{s + j\omega}$ |
| $\cos(\omega t + \phi)$ | $\frac{s \cos \phi - \omega \sin \phi}{s^2 + \omega^2}$ |
| $e^{-at} \cos \omega t$ | $\frac{s + a}{(s + a)^2 + \omega^2}$ |
| $e^{-at} \sin \omega t$ | $\frac{\omega}{(s + a)^2 + \omega^2}$ |
